The formulae below may be of use to you.

$F_g = \frac{GMm}{r^2}$ $F_c = \frac{mv^2}{r}$ $\Delta p = F\Delta t$ $\omega = 2\pi f$ $d = r\theta$ $v = r\omega$ $a = r\alpha$ $W = Fd$ $F_{net} = ma$ $p = mv$ $x_{COM} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$ $\omega = \frac{\Delta\theta}{\Delta t}$ $\alpha = \frac{\Delta\omega}{\Delta t}$ $L = I\omega$ $L = mvr$ $\tau = I\alpha$ $\tau = Fr$ $E_{K(ROT)} = \frac{1}{2}I\omega^2$ $E_{K(LIN)} = \frac{1}{2}mv^2$ $\Delta E_p = mgh$ $\omega_f = \omega_i + \alpha t$ $\omega_f^2 = \omega_i^2 + 2\alpha\theta$ $\theta = \frac{(\omega_i + \omega_f)t}{2}$ $\theta = \omega_i t + \frac{1}{2}\alpha t^2$	$T = 2\pi\sqrt{\frac{l}{g}}$ $T = 2\pi\sqrt{\frac{m}{k}}$ $E_p = \frac{1}{2}ky^2$ $F = -ky$ $a = -\omega^2 y$ $y = A\sin\omega t$ $y = A\cos\omega t$ $v = A\omega\cos\omega t$ $v = -A\omega\sin\omega t$ $a = -A\omega^2\sin\omega t$ $a = -A\omega^2\cos\omega t$ $\Delta E = Vq$ $P = VI$ $V = Ed$ $Q = CV$ $C_T = C_1 + C_2$ $\frac{1}{C_T} = \frac{1}{C_1} + \frac{1}{C_2}$ $E = \frac{1}{2}QV$ $C = \frac{\varepsilon_o \varepsilon_r A}{d}$ $\tau = RC$ $\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2}$ $R_T = R_1 + R_2$ $V = IR$ $F = BIL$	$\phi = BA$ $\varepsilon = -\frac{\Delta\phi}{\Delta t}$ $\varepsilon = -L\frac{\Delta I}{\Delta t}$ $\frac{N_p}{N_s} = \frac{V_p}{V_s}$ $E = \frac{1}{2}LI^2$ $\tau = \frac{L}{R}$ $I = I_{MAX}\sin\omega t$ $V = V_{MAX}\sin\omega t$ $I_{MAX} = \sqrt{2}\,I_{rms}$ $V_{MAX} = \sqrt{2}\,V_{rms}$ $X_C = \frac{1}{\omega C}$ $X_L = \omega L$ $V = IZ$ $f_0 = \frac{1}{2\pi\sqrt{LC}}$ $n\lambda = \frac{dx}{L}$ $n\lambda = d\sin\theta$ $f' = f\frac{V_W}{V_W \pm V_S}$ $E = hf$ $hf = \phi + E_K$ $E = \Delta mc^2$ $\frac{1}{\lambda} = R\left(\frac{1}{S^2} - \frac{1}{L^2}\right)$ $E_n = -\frac{hcR}{n^2}$ $v = f\lambda$ $f = \frac{1}{T}$